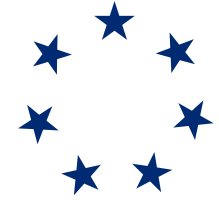


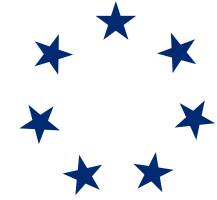
# Memory Management



Instructor: Hengming Zou, Ph.D.



In Pursuit of Absolute Simplicity 求于至简，归于永恒

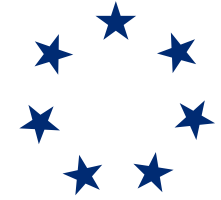


# Lecture Arrangement

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- ➔ Four lectures:
- ➔ Lecture 1: (3)
  - Basic memory management
- ➔ Lecture 2: (3)
  - Paging systems
- ➔ Lecture 3: (2)
  - Segmentation systems



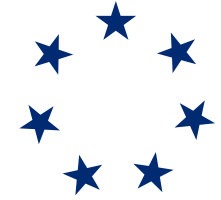


# Lecture 1: Basic memory management

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- ➔ Memory management environment
- ➔ Fixed location
- ➔ Base and bound
- ➔ Address translation
- ➔ Swapping
- ➔ Virtual memory



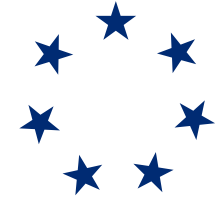


## Lecture 2: Paging systems

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- ➔ Paging
- ➔ Page table
- ➔ Page replacement
- ➔ Design issues for paging systems



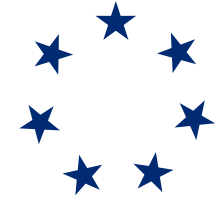


## Lecture 3: Segmentation Systems

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- ➔ Drawback of paging system
- ➔ Segmentation systems
- ➔ Segmentation with paging
- ➔ Case study: Multics





## Lecture 4: Advanced Topics

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- ➔ Translation data
- ➔ Kernel vs. User Mode
- ➔ Passing Arguments to System Call
- ➔ Separation of Policy and Mechanism
- ➔ Case study: Linux Memory Management



# Basic Memory Management



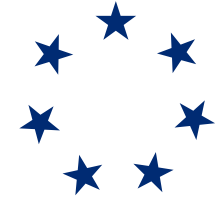
# Content

---

- ➔ Memory management environment
- ➔ Memory hierarchy and virtual memory
- ➔ (Pure) segmentation
- ➔ Fixed location
- ➔ Fixed Partition
  - Address translation
  - Base and bound
- ➔ Swapping



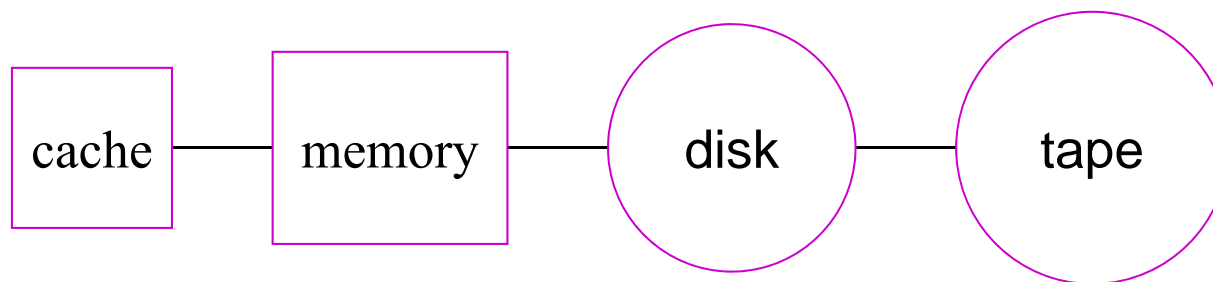




# Memory Management Environment

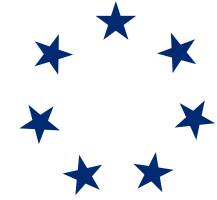
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- ➔ Ideally programmers want memory that is
  - Large, fast, and non volatile
- ➔ The Reality: the memory hierarchy:
  - Cache: Small amount of fast, expensive memory –
  - Main memory: Some medium-speed, medium price memory
  - Disk storage: Gigabytes of slow, cheap memory



Memory hierarchy

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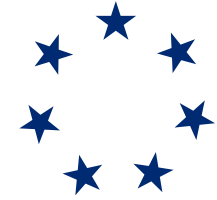


# Memory Management Environment

---

- ➔ Memory manager handles the memory hierarchy
  - through virtual memory
- ➔ What is virtual memory:
  - An illusion provided to the applications
  - Built on top of the memory hierarchy
- ➔ Provides two abstractions:
  - an address space that can be larger than the amount of physical memory
  - a storage space that is fast than the physical memory
- ➔ In the future will provide a storage space that is durable





# Memory Management Objective

---

- ➔ Meet two address objectives:
- ➔ **Address independence**
  - The address given by program is independent of physical address
- ➔ **Address protection**
  - One process does not access another's address space



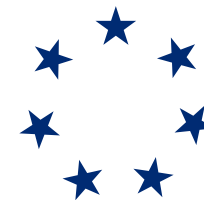


# Basic Memory Management

---

- ➔ Pure Segmentation
  - Treat each program as a single logical segment
  
- ➔ Can be further divided into:
- ➔ Fixed location
  - Applies to uni-programming
- ➔ Fixed partitions
  - Applies to multi-programming
- ➔ Swapping
  - Applies to multi-programming

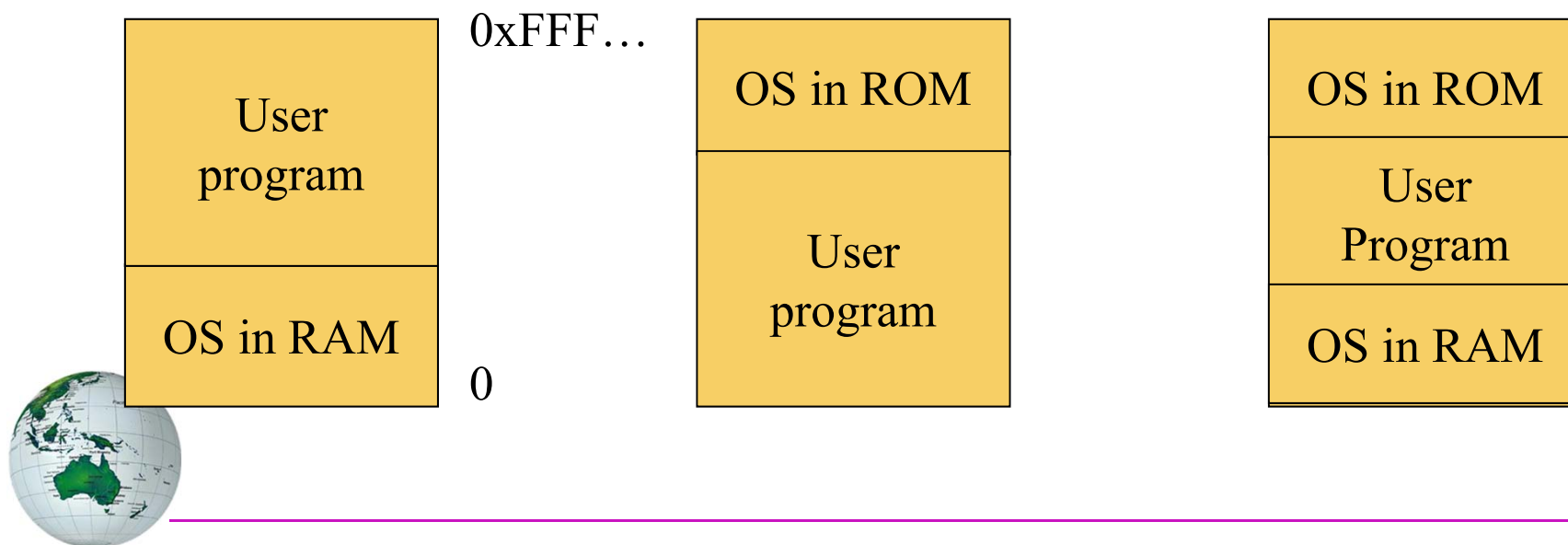


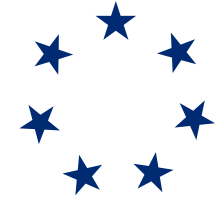


## Fixed Location for Uni-programming

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- ➔ One process runs at a time
  - One process occupies memory at a time
- ➔ Always load process into the same memory spot
- ➔ And reserve some space for the OS
- ➔ 3 ways of organizing memory for an OS with one user process





# Fixed Location for Uni-programming

---

- ➔ Achieves address independence by
  - Loading process into same physical memory location
  - Therefore physical addresses can be computed before hand
- ➔ Achieve address protection by:
  - Doing nothing!
- ➔ Problems with uni-programming?
  - Load processes in its entirety (no enough space?)
  - Waste resource (both CPU and Memory)





# Multi-programming

---

- ➔ More than one process is in memory at a time
  
- ➔ More must be done by memory management
  - Need to support address translation
    - Address from instruction may not be the final address
    - Physical addresses cannot be computed before hand
  - Need to support protection
    - Each process cannot access other processes' space





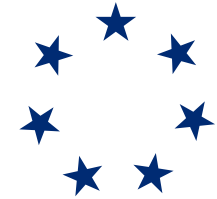
# Multiprogramming with Fixed Partitions

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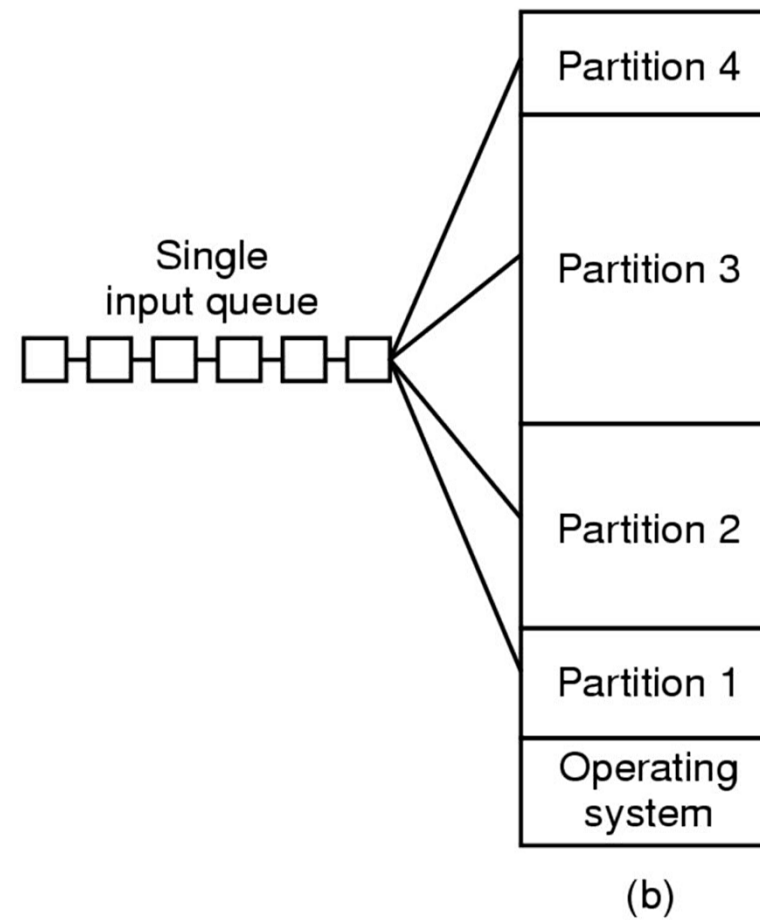
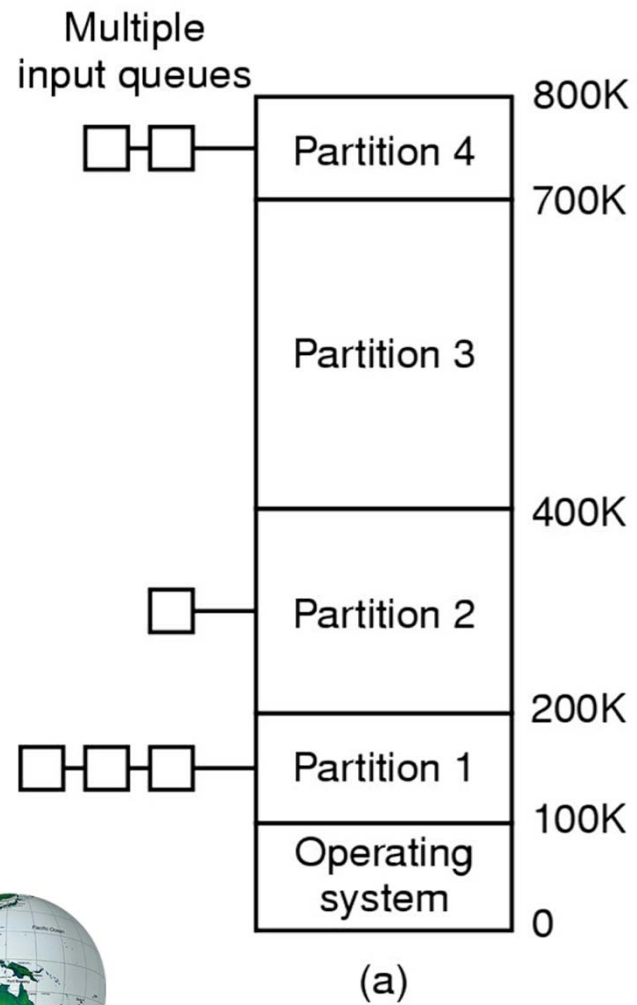
- ➔ The simplest form of memory mgmt for multiprogramming
  - Memory are partitioned into fixed-size partitions
  - Programs are loaded into fixed partitions
  
- ➔ Two options exist for loading programs into fixed memory partitions
  - Separate input queues for each partition
    - Incoming processes are allocated into fixed partition
  - Single input queue
    - Incoming processes can go to any partition
    - Assume partition is big enough to hold the processes

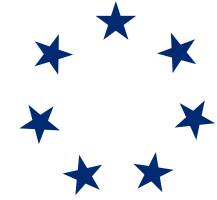






# Multiprogramming with Fixed Partitions



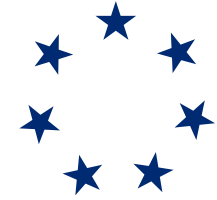


# Multiprogramming Issues

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- ➔ Cannot be sure where program will be loaded
  - Many partitions exist that can be used to hold the program
  - Address locations of variables can not be absolute
  - Code routines cannot be absolute
- ➔ Solution:
  - Use base and limit values
  - Address added to base value to map to physical address
  - Address locations larger than limit value is an error





# Multiprogramming Issues

---

- ➔ Protection processes from each other
  - Must keep a program out of other processes' partitions
- ➔ Solution:
  - Address translation
  - Must translate addresses issued by a process
    - so they don't conflict with addresses issued by other processes





# Address Translation

---

## ➔ Static address translation

- Translate addresses before execution
- Translation remains constant during execution

## ➔ Dynamic address translation

- Translate addresses during execution
- Translation may change during execution



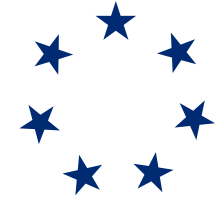


# Address Translation

---

- ➔ Is it possible to:
  - Run two processes at the same time (both in memory), and
  - provide address independence with only static address translation?
- ➔ Does this achieve the other address space objective?
  - No (i.e. does not offer address protection)
- ➔ Achieving all address space objectives (**protection/independence**)
  - requires doing some work on every memory reference
- ➔ Solution:
  - Dynamic address translation





# Dynamic Address Translation

---

- ➔ Translate every memory reference from virtual to physical address
- ➔ Virtual address:
  - An address viewed by the user process
  - The abstraction provided by the OS
- ➔ Physical address
  - An address viewed by the physical memory



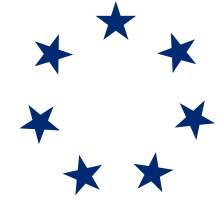


# Benefit of Dynamic Translation

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- ➔ Enforces protection
  - One process can't refer to another process's address space
  
- ➔ **Enables virtual memory**
  - A virtual address only needs to be in physical memory
    - when it's being accessed
  - Change translations on the fly
    - as different virtual addresses occupy physical memory
  
- ➔ Does dynamic address translation require hardware support?
  - It's better to have but not absolutely necessary





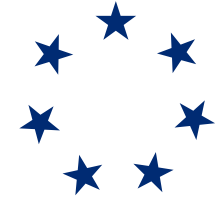
# Implement Translator

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- ➔ Lots of ways to implement the translator
- ➔ Tradeoffs among:
  - Flexibility (e.g. sharing, growth, virtual memory)
  - Size of translation data
  - Speed of translation





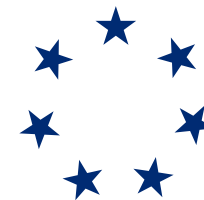


## Base and Bounds

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- ➔ The simplest solution
- ➔ Load each process into contiguous regions of physical memory
- ➔ Prevent each process from accessing data outside its region
  
- ➔ if (virtual address > bound) {
- ➔     trap to kernel; kill process (core dump)
- ➔ } else {
- ➔     physical address = virtual address + base
- ➔ }

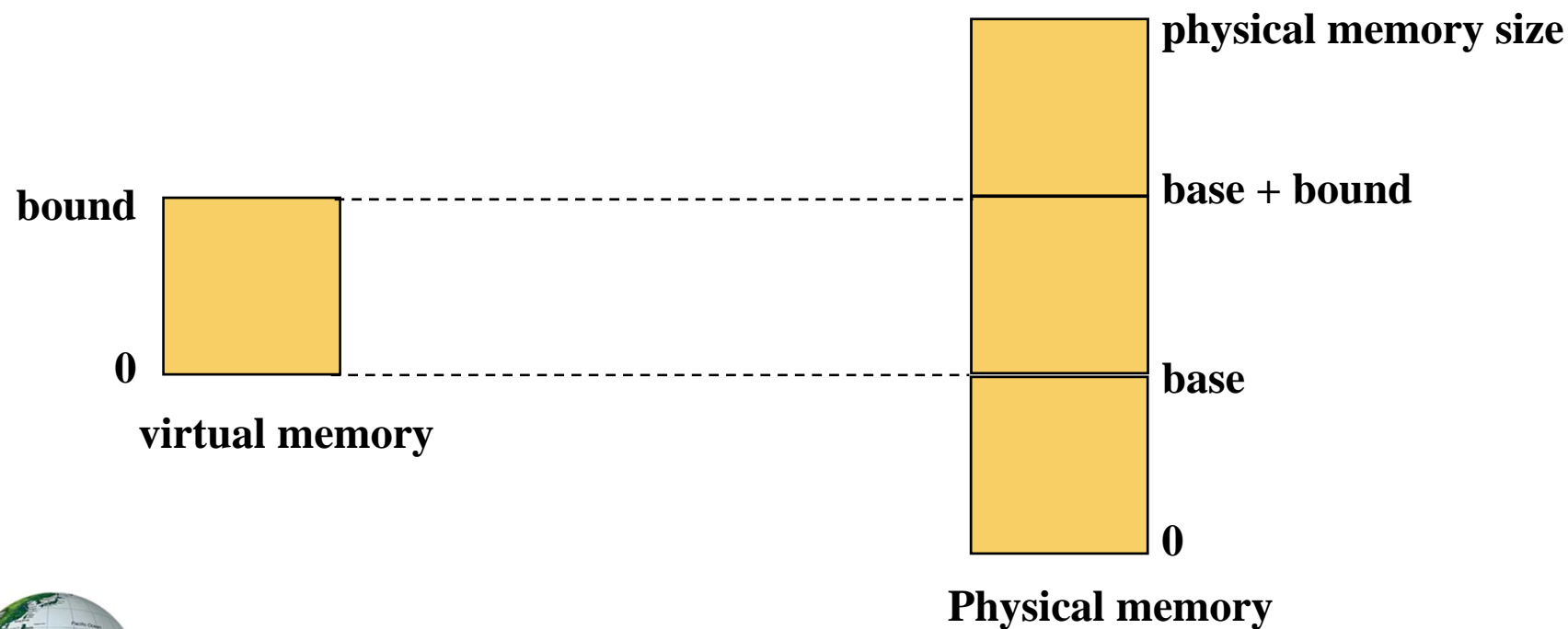


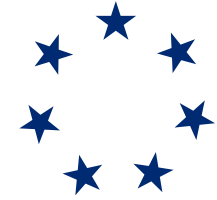


# Base and Bounds

---

- ➔ Process has illusion of running on its own dedicated machine
  - with memory  $[0, \text{bound})$





# Base and Bounds

---

- ➔ This is similar to linker-loader
  - But also protect processes from each other
- ➔ Only kernel can change base and bounds
- ➔ During context switch, must change all translation data
  - (base and bounds registers)
  
- ➔ What to do when address space grows?





# Pros and Cons of Base and Bounds

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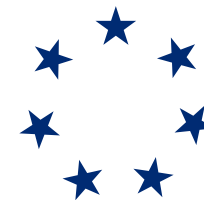
## ➔ Pros:

- Low hardware cost
  - 2 registers, adder, comparator
- Low overhead
  - Add and compare on each memory reference

## ➔ Cons:

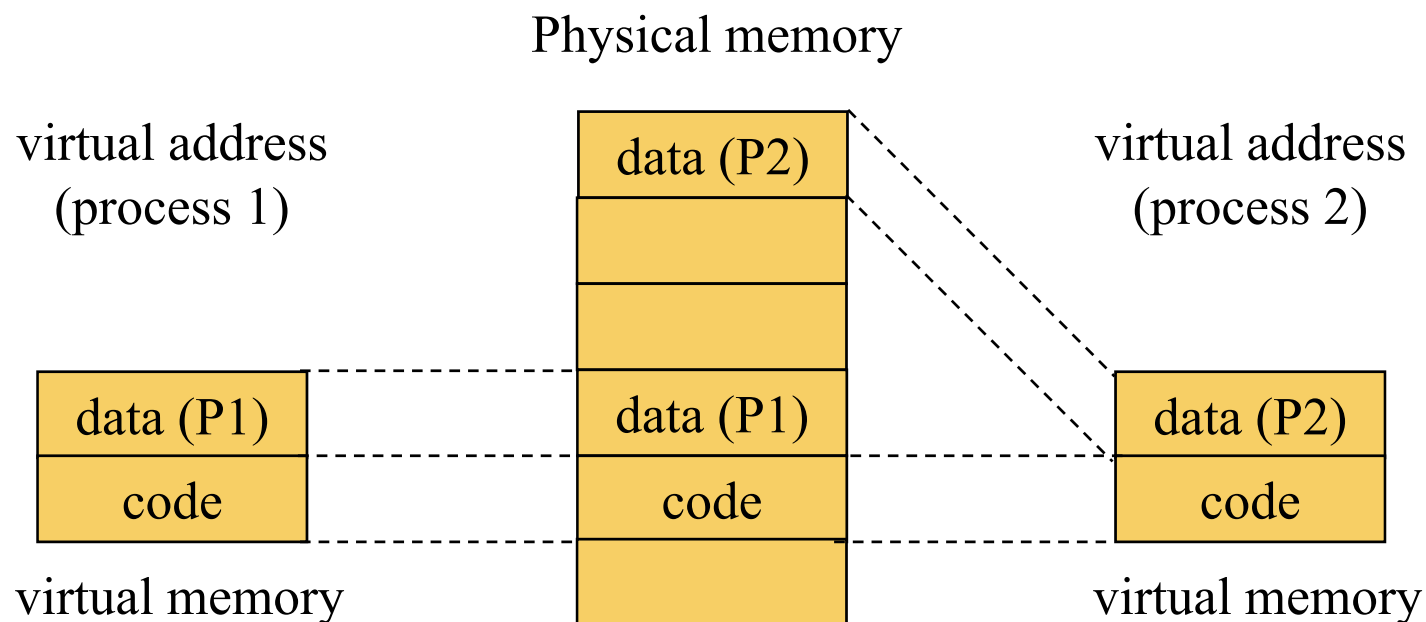
- Hard for a single address space to be larger than physical memory
- But sum of all address spaces can be larger than physical memory
  - Swap an entire address space out to disk
  - Swap address space for new process in





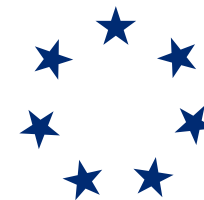
## Cons of Base and Bounds

- ➔ Can't share part of an address space between processes



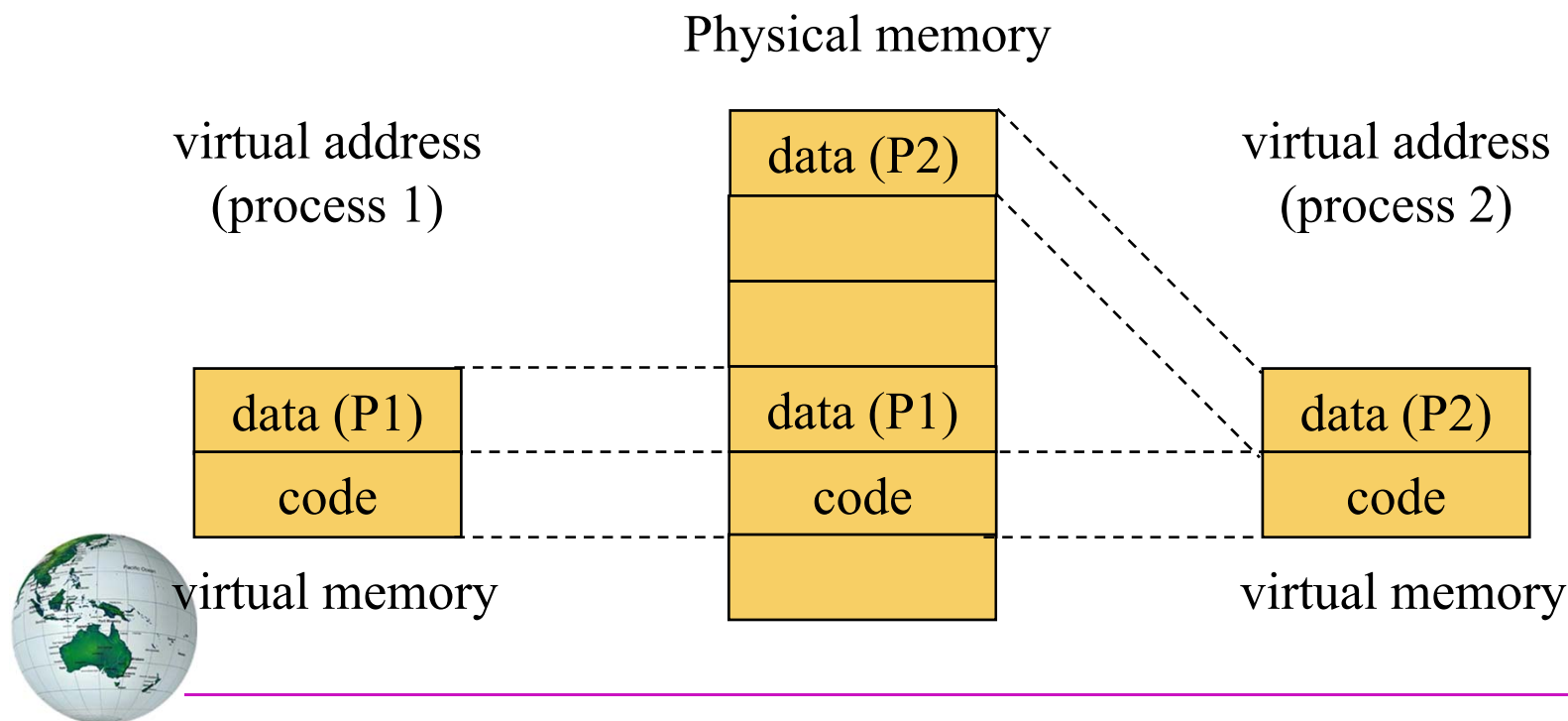
Does this work under base and bound?

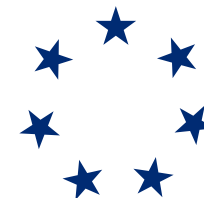




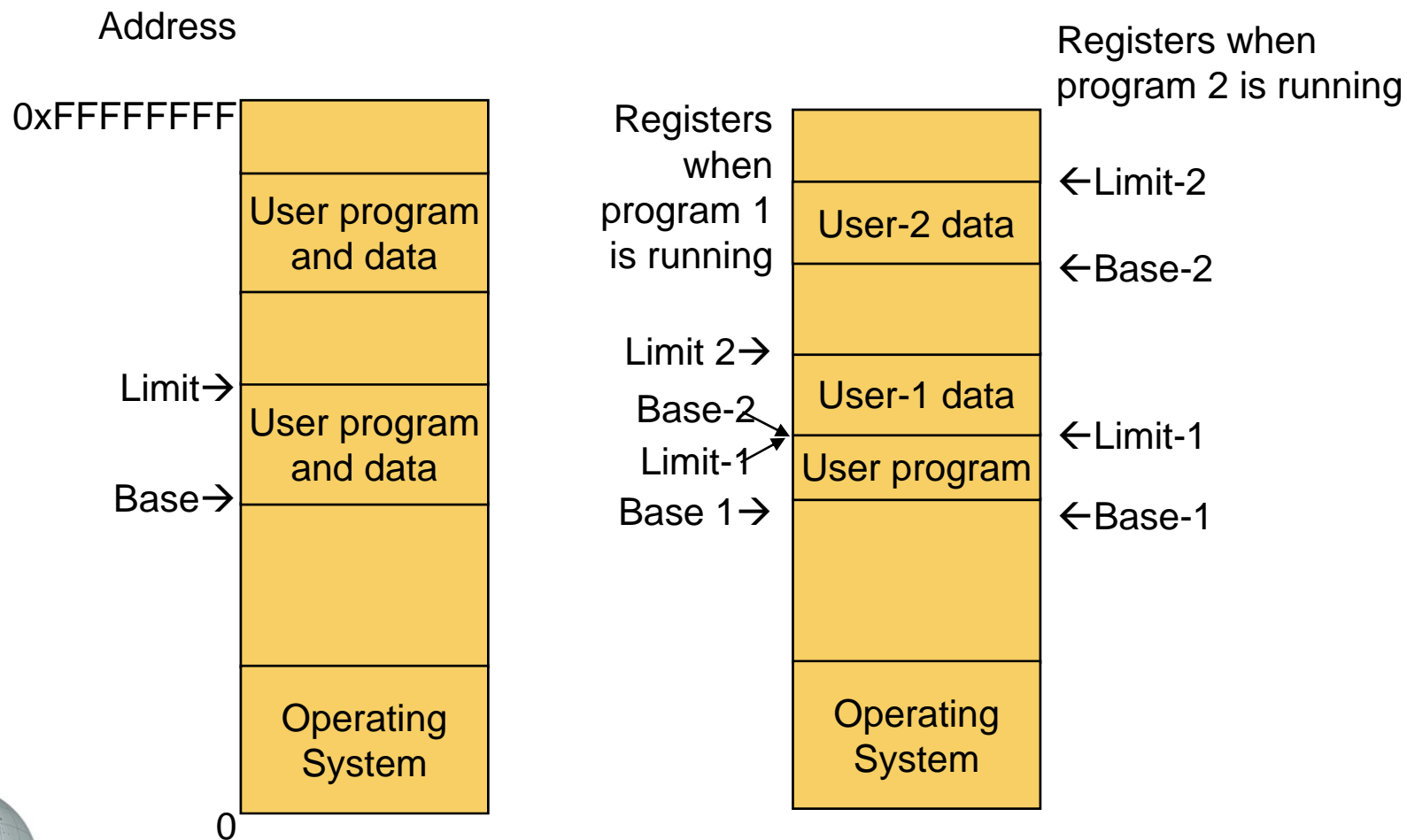
## Cons of Base and Bounds

- ➔ Solution:
- ➔ Multiple sets of base and bounds
  - Specifically, use two sets of base and bounds for two processes sharing
    - one for code section, one for data section



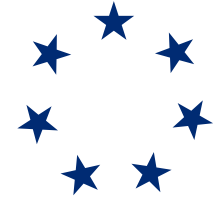


# 1 Base-Limit & 2 Base-Limit Pairs



# Swapping

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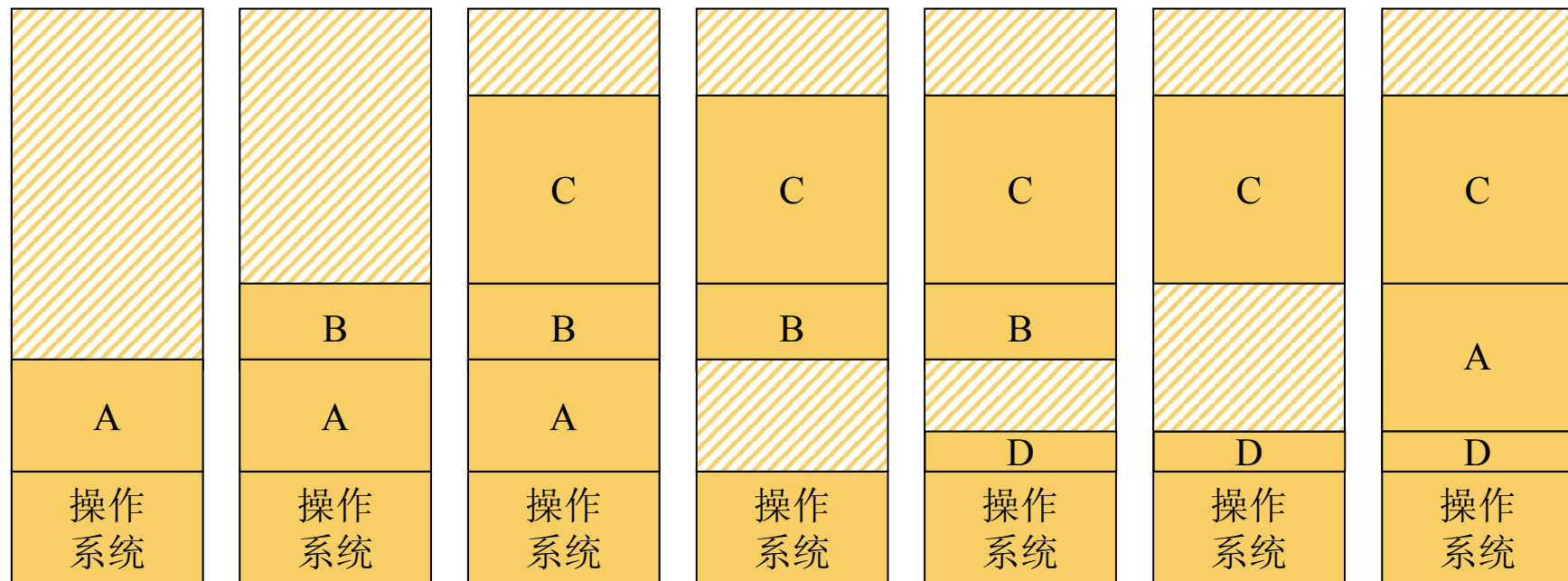
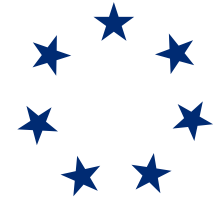


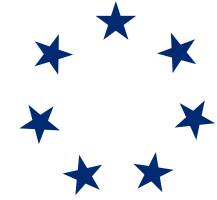
- ➔ Fixed partitions is inflexible in utilizing the physical memory space
- ➔ A flexible management scheme allows varying partitions
  
- ➔ Swapping is the solution:
  - **Take processes out from memory and bring process into memory**
  
- ➔ Memory allocation changes as:
  - Processes come into memory
  - Processes leave memory





# Swapping





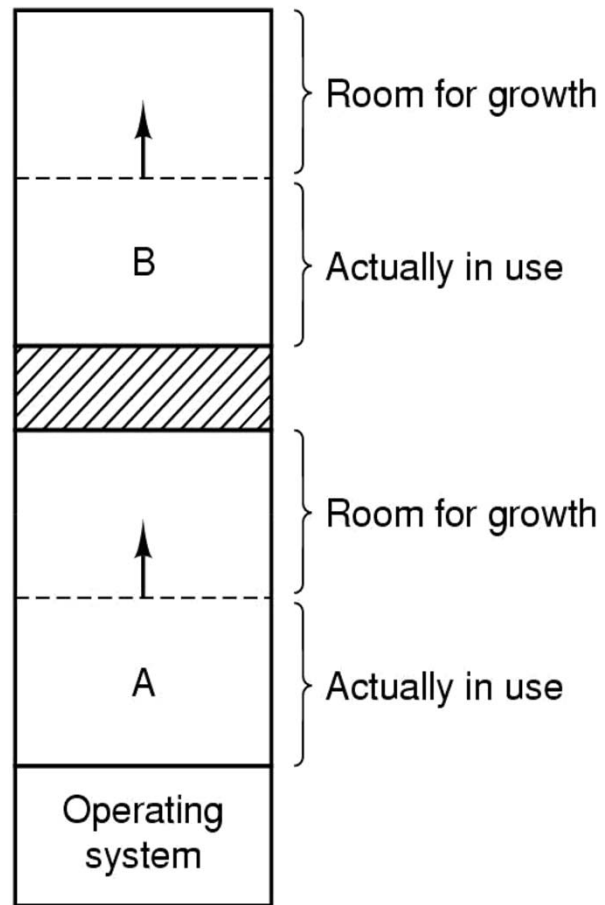
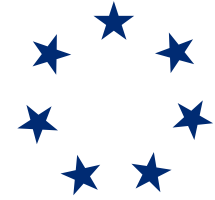
# Swapping

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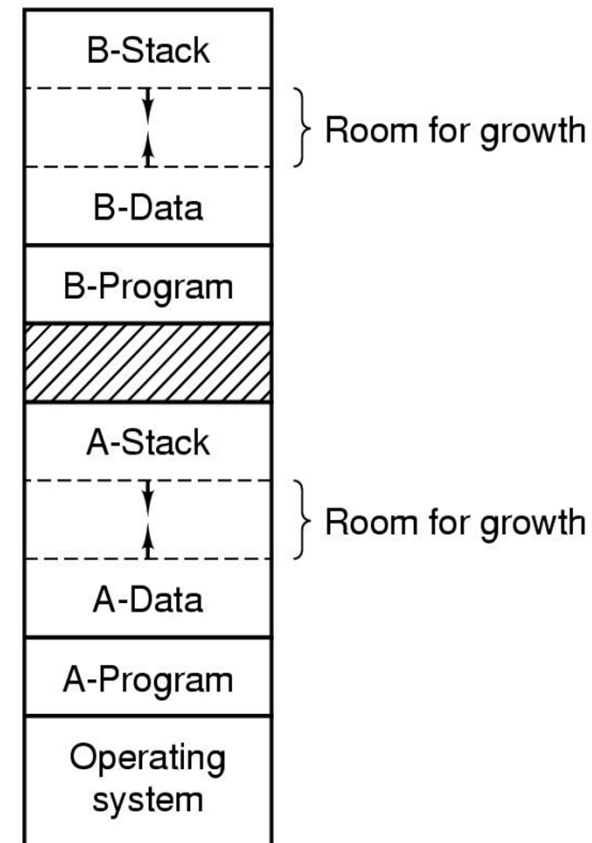
- ➔ Problem with previous situation?
- ➔ Difficult to grow process space
  - i.e. stack, data, etc.
- ➔ Solution:
  - Allocating space for growing data segment
  - Allocating space for growing stack & data segment



# Swapping



(a)



(b)





## External Fragmentation with Swap

---

- ➔ In a swap system, processes come and go
- ➔ Can leave a mishmash of available memory regions
- ➔ Some regions may be too small to be of any use
- ➔ Hard to grow address space
  - Might have to move to different region of physical memory (which is slow)



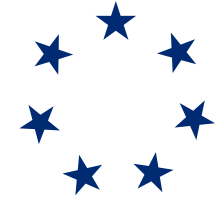


# External Fragmentation

---

- ➔ P1 start:100 KB (phys. mem. 0-99 KB)
- ➔ P2 start:200 KB (phys. mem. 100-299 KB)
- ➔ P3 start:300 KB (phys. mem. 300-599 KB)
- ➔ P4 start:400 KB (phys. mem. 600-999 KB)
- ➔ P3 exits (frees phys. mem. 300-599 KB)
- ➔ P5 start:100 KB (phys. mem. 300-399 KB)
- ➔ P1 exits (frees phys. mem. 0-99 KB)
- ➔ P6 start:300 KB





# External Fragmentation

---

- ➔ 300 KB are free (400-599 KB; 0-99 KB)
  - but not contiguous
- ➔ This is called “external fragmentation”
  - wasted memory between allocated regions
- ➔ Can waste lots of memory





# Strategies to Minimize Fragmentation

---

- ➔ Best fit:
  - Allocate the smallest memory region that can satisfy the request
    - (least amount of wasted space)
- ➔ First fit:
  - Allocate the memory region that you find first that can satisfy the request
- ➔ In worst case, must re-allocate existing memory regions
  - by copying them to another area





## Problem with Pure Segmentation

---

- ➔ Hard to grow address space (for a data structure for example)
- ➔ Unable to run program that is larger than physical memory
- ➔ External fragmentation
  
- ➔ How to extend more than one contiguous data structure in VM?
- ➔ How to run a program larger than physical memory?
  - PAGING





The background of the image is a green-tinted photograph of a glass bottle. Inside the bottle, a small plant with thin, green, needle-like leaves is visible. The bottle is centered, and the text is overlaid on it. The overall effect is a soft, ethereal green glow.

Computer Changes Life